

# NLP Programming Tutorial 11 - The Structured Perceptron

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# Prediction Problems

Given  $x$ , predict  $y$

## A book review

Oh, man I love this book!  
This book is so boring...

## Is it positive?

yes  
no

Binary  
Prediction  
(2 choices)

## A tweet

On the way to the park!  
公園に行くなう!

## Its language

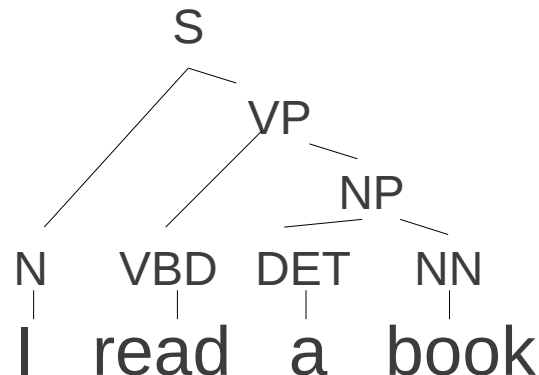
English  
Japanese

Multi-class  
Prediction  
(several choices)

## A sentence

I read a book

## Its syntactic parse



Structured  
Prediction  
(millions of choices)  
2

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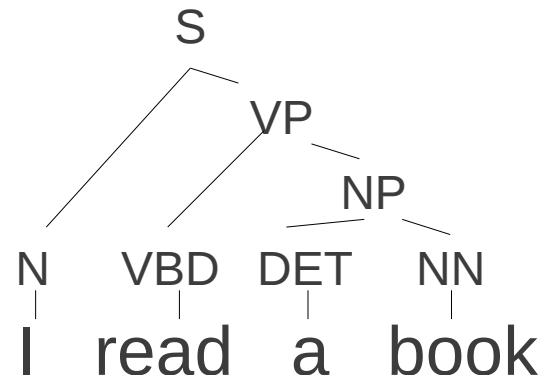
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Most NLP  
Problems!

Structured  
Prediction  
(millions of choices)

# So Far, We Have Learned

## Classifiers

Perceptron, SVM, Neural Net

Lots of features

Binary prediction

## Generative Models

HMM POS Tagging  
CFG Parsing

Conditional probabilities

Structured prediction

# Structured Perceptron

## Classifiers

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## Generative Models

HMM POS Tagging  
CFG Parsing

Conditional probabilities

Structured prediction

Structured perceptron →  
Classification with lots of features  
over structured models!

# Uses of Structured Perceptron (or Variants)

- **POS Tagging with HMMs**

Collins “Discriminative Training Methods for Hidden Markov Models: Theory and Experiments with Perceptron Algorithms” ACL02

- **Parsing**

Huang+ “Forest Reranking: Discriminative Parsing with Non-Local Features” ACL08

- **Machine Translation**

Liang+ “An End-to-End Discriminative Approach to Machine Translation” ACL06

(Neubig+ “Inducing a Discriminative Parser for Machine Translation Reordering, EMNLP12”, Plug :) )

- **Discriminative Language Models**

Roark+ “Discriminative Language Modeling with Conditional Random Fields and the Perceptron Algorithm” ACL04

# Example:

## Part of Speech (POS) Tagging

- Given a sentence  $X$ , predict its part of speech sequence  $Y$

Natural language processing ( NLP ) is a field of computer science

↓ ↓ ↓ ↓ ↓ ↓ ↓ ↓ ↓ ↓ ↓ ↓ ↓ ↓

JJ NN NN -LRB- NN -RRB- VBZ DT NN IN NN NN

- A type of structured prediction

# Hidden Markov Models (HMMs) for POS Tagging

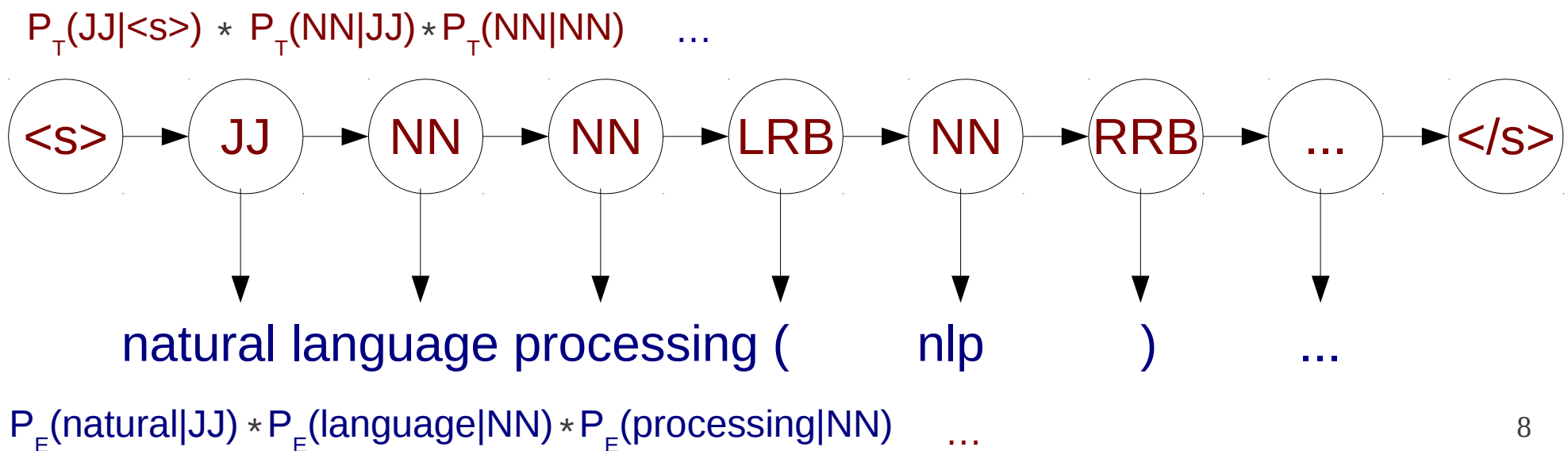
- POS → POS **transition** probabilities

- Like a bigram model!

$$P(Y) \approx \prod_{i=1}^{l+1} P_T(y_i | y_{i-1})$$

- POS → Word **emission** probabilities

$$P(X|Y) \approx \prod_1^l P_E(x_i | y_i)$$





# Why are Features Good?

- Can easily try many different ideas
  - Are capital letters usually nouns?
  - Are words that end with -ed usually verbs? -ing?

# Restructuring HMM With Features

Normal HMM: 
$$P(X, Y) = \prod_{i=1}^l P_E(x_i | y_i) \prod_{i=1}^{l+1} P_T(y_i | y_{i-1})$$

# Restructuring HMM With Features

Normal HMM: 
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Log Likelihood: 
$$\log P(X, Y) = \sum_{i=1}^l \log P_E(x_i | y_i) + \sum_{i=1}^{l+1} \log P_T(y_i | y_{i-1})$$

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Score 
$$S(X, Y) = \sum_{i=1}^l w_{E, y_i, x_i} + \sum_{i=1}^{l+1} w_{T, y_{i-1}, y_i}$$

# Restructuring HMM With Features

Normal HMM: 
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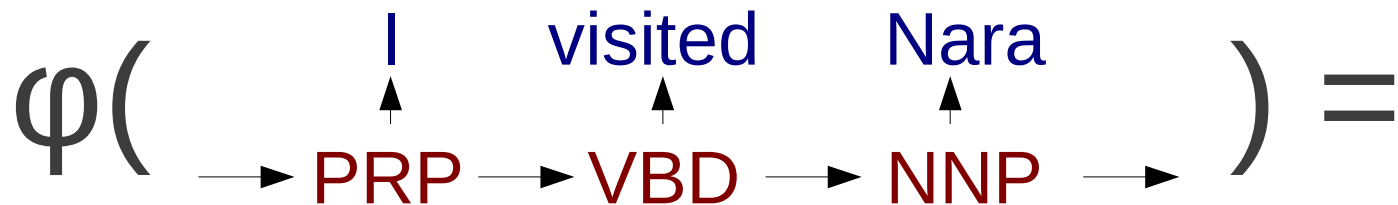
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Score 
$$S(X, Y) = \sum_{i=1}^l w_{E, y_i, x_i} + \sum_{i=1}^{l+1} w_{T, y_{i-1}, y_i}$$

When: 
$$w_{E, y_i, x_i} = \log P_E(x_i | y_i) \quad w_{T, y_{i-1}, y_i} = \log P_T(y_i | y_{i-1})$$

$$\log P(X, Y) = S(X, Y)$$

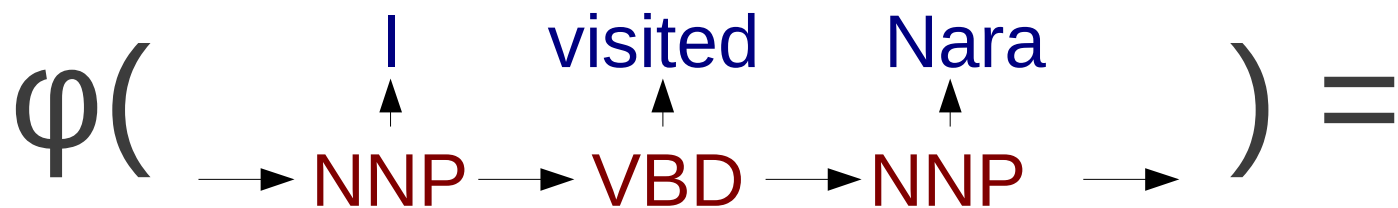
# Example



$$\varphi_{T,<S>,\text{PRP}}(X, Y_1) = 1 \quad \varphi_{T,\text{PRP},\text{VBD}}(X, Y_1) = 1 \quad \varphi_{T,\text{VBD},\text{NNP}}(X, Y_1) = 1 \quad \varphi_{T,\text{NNP},</S>}(X, Y_1) = 1$$

$$\varphi_{E,\text{PRP},\text{"I"}}(X, Y_1) = 1 \quad \varphi_{E,\text{VBD},\text{"visited"}}(X, Y_1) = 1 \quad \varphi_{E,\text{NNP},\text{"Nara"}}(X, Y_1) = 1$$

$$\varphi_{\text{CAPS},\text{PRP}}(X, Y_1) = 1 \quad \varphi_{\text{CAPS},\text{NNP}}(X, Y_1) = 1 \quad \varphi_{\text{SUF},\text{VBD},\text{"...ed"}}(X, Y_1) = 1$$



$$\varphi_{T,<S>,\text{NNP}}(X, Y_1) = 1 \quad \varphi_{T,\text{NNP},\text{VBD}}(X, Y_1) = 1 \quad \varphi_{T,\text{VBD},\text{NNP}}(X, Y_1) = 1 \quad \varphi_{T,\text{NNP},</S>}(X, Y_1) = 1$$

$$\varphi_{E,\text{NNP},\text{"I"}}(X, Y_1) = 1 \quad \varphi_{E,\text{VBD},\text{"visited"}}(X, Y_1) = 1 \quad \varphi_{E,\text{NNP},\text{"Nara"}}(X, Y_1) = 1$$

$$\varphi_{\text{CAPS},\text{NNP}}(X, Y_1) = 2 \quad \varphi_{\text{SUF},\text{VBD},\text{"...ed"}}(X, Y_1) = 1$$

# Finding the Best Solution

- We must find the POS sequence that satisfies:

$$\hat{Y} = \operatorname{argmax}_Y \sum_i w_i \phi_i(X, Y)$$

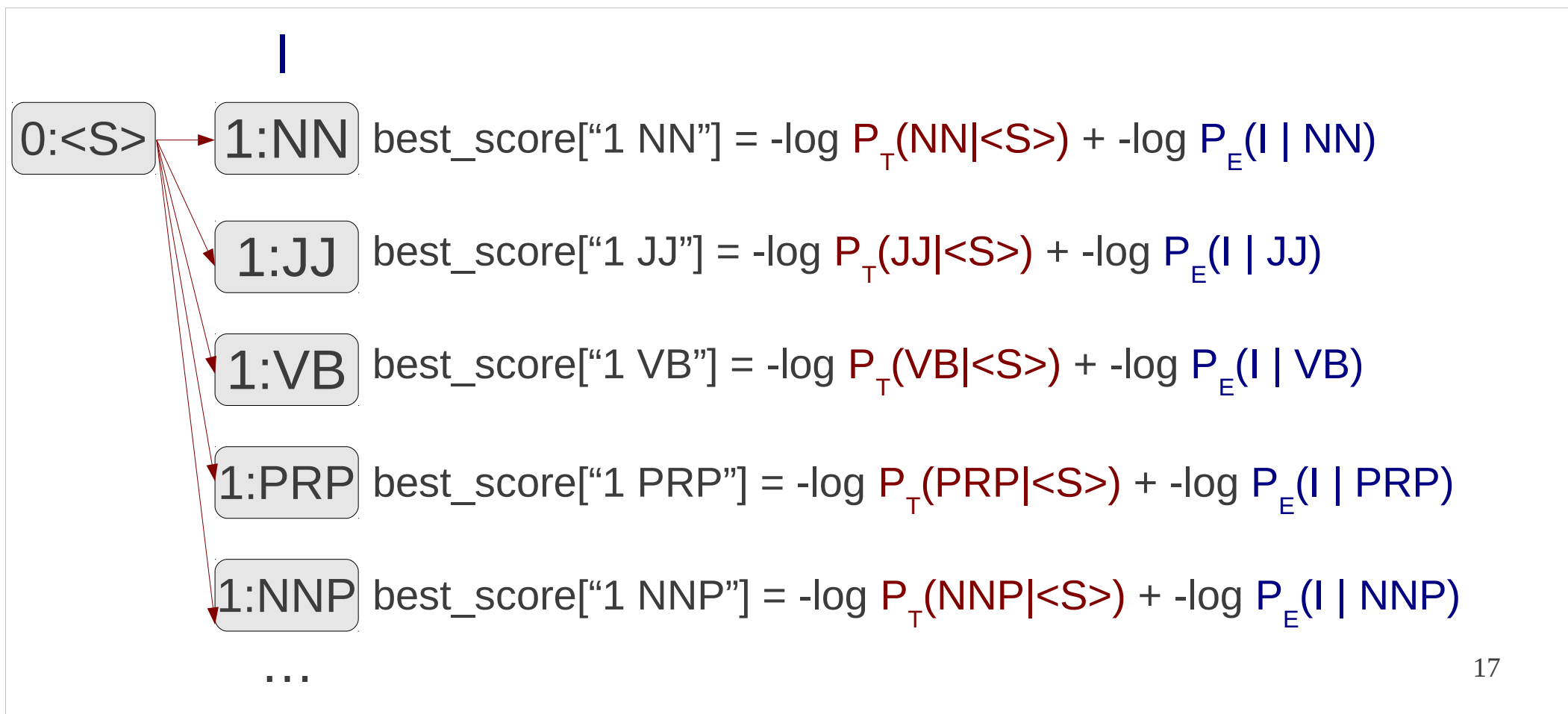
# Remember: HMM Viterbi Algorithm

- **Forward step**, calculate the best path to a node
  - Find the path to each node with the **lowest negative log probability**
- **Backward step**, reproduce the path
  - This is easy, almost the same as word segmentation



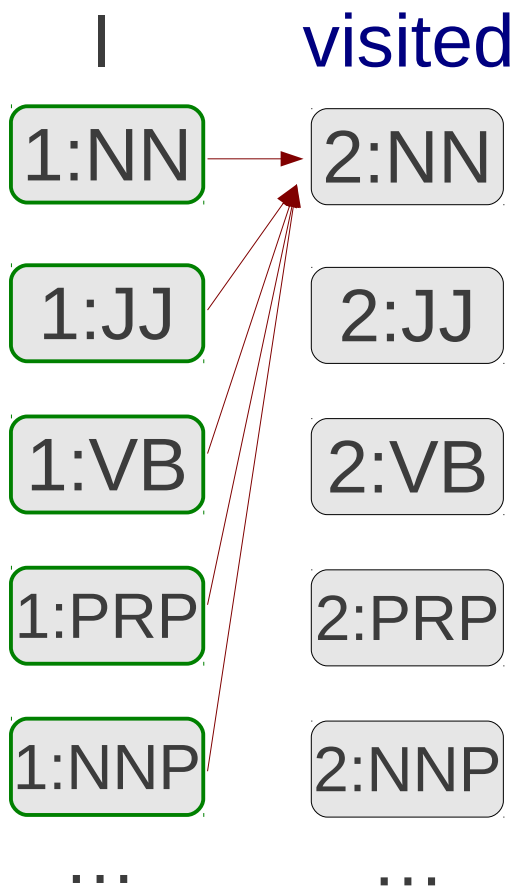
# Forward Step: Part 1

- First, calculate transition from  $\langle S \rangle$  and emission of the first word for every POS



# Forward Step: Middle Parts

- For middle words, calculate the minimum score for all possible previous POS tags



```

best_score["2 NN"] = min(
  best_score["1 NN"] + -log PT(NN|NN) + -log PE(visited | NN),
  best_score["1 JJ"] + -log PT(NN|JJ) + -log PE(language | NN),
  best_score["1 VB"] + -log PT(NN|VB) + -log PE(language | NN),
  best_score["1 PRP"] + -log PT(NN|PRP) + -log PE(language | NN),
  best_score["1 NNP"] + -log PT(NN|NNP) + -log PE(language | NN),
  ...
)
best_score["2 JJ"] = min(
  best_score["1 NN"] + -log PT(JJ|NN) + -log PE(language | JJ),
  best_score["1 JJ"] + -log PT(JJ|JJ) + -log PE(language | JJ),
  best_score["1 VB"] + -log PT(JJ|VB) + -log PE(language | JJ),
  ...
  
```

# HMM Viterbi with Features

- Same as probabilities, use feature weights



# HMM Viterbi with Features

- Can add additional features



# Learning In the Structured Perceptron

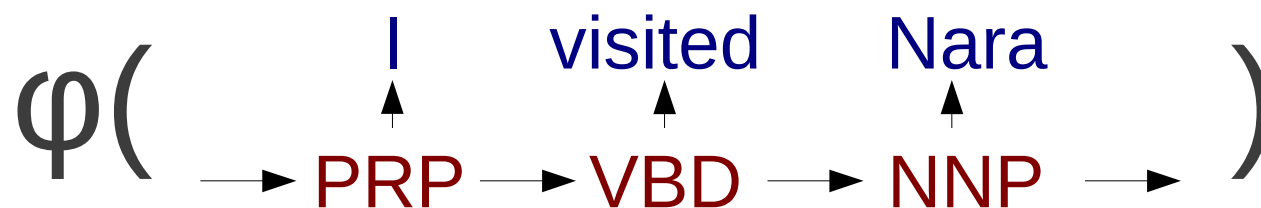
- Remember the perceptron algorithm
- If there is a mistake:

$$\mathbf{w} \leftarrow \mathbf{w} + y \phi(\mathbf{x})$$

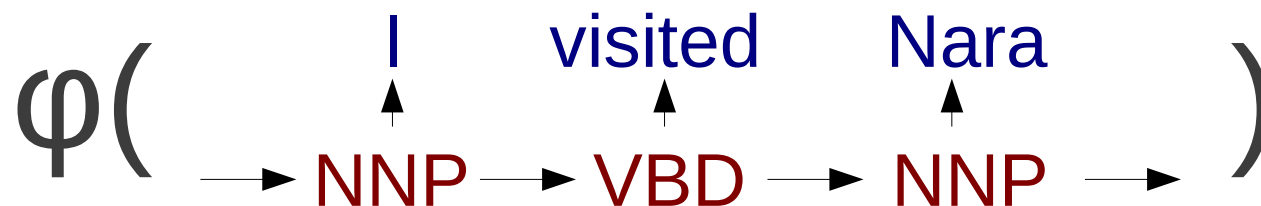
- Update weights to:
  - increase score of positive examples
  - decrease score of negative examples
- What is positive/negative in structured perceptron?

# Learning in the Structured Perceptron

- Positive example, correct feature vector:

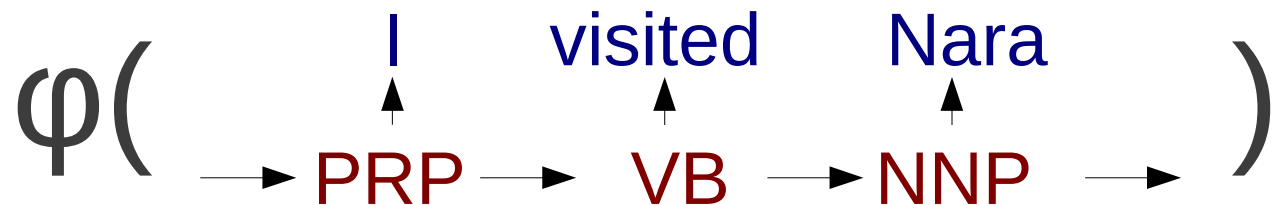
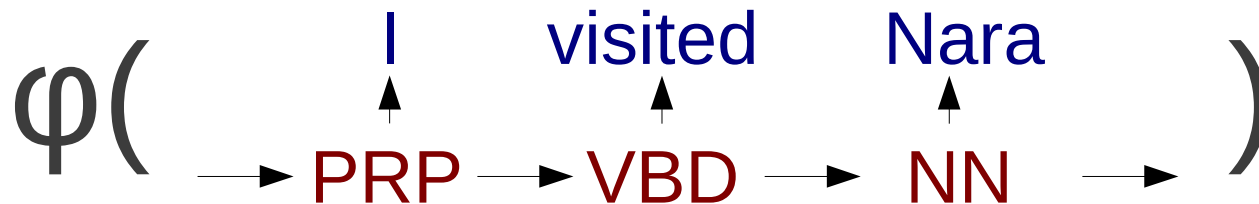
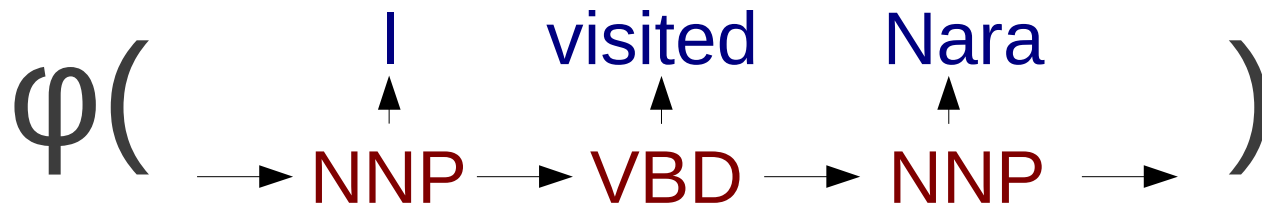


- Negative example, incorrect feature vector:



# Choosing an Incorrect Feature Vector

- There are too many incorrect feature vectors!



- Which do we use?

# Choosing an Incorrect Feature Vector

- Answer: We update using the incorrect answer with the highest score:

$$\hat{Y} = \operatorname{argmax}_Y \sum_i w_i \phi_i(X, Y)$$

- Our update rule becomes:

$$\mathbf{w} \leftarrow \mathbf{w} + \phi(X, Y') - \phi(X, \hat{Y})$$

- ( $Y'$  is the correct answer)
- Note: If highest scoring answer is correct, no change



# Structured Perceptron Algorithm

```
create map  $w$ 
for / iterations
  for each labeled pair  $X$ ,  $Y_{prime}$  in the data
     $Y_{hat} = \text{HMM\_VITERBI}(w, X)$ 
     $\phi_{prime} = \text{CREATE\_FEATURES}(X, Y_{prime})$ 
     $\phi_{hat} = \text{CREATE\_FEATURES}(X, Y_{hat})$ 
     $w += \phi_{prime} - \phi_{hat}$ 
```

# Creating HMM Features

- Make “create features” for each transition, emission

CREATE\_TRANS ( **NNP,VBD** )



$\phi["T,NNP,VBD"] = 1$

CREATE\_EMIT ( **NNP,Nara** )



$\phi["E,NNP,Nara"] = 1$

$\phi["CAPS,NNP"] = 1$

# Creating HMM Features

- The `CREATE_FEATURES` function does for all words

```
CREATE_FEATURES(X, Y):  
  create map phi  
  for i in 0 .. |Y|:  
    if i == 0: first_tag = "<s>"  
    else:      first_tag = Y[i-1]  
    if i == |Y|: next_tag = "</s>"  
    else:      next_tag = Y[i]  
    phi += CREATE_TRANS(first_tag, next_tag)  
  for i in 0 .. |Y|-1:  
    phi += CREATE_EMIT(Y[i], X[i])  
  return phi
```

# Viterbi Algorithm Forward Step

**split** *line* into words

$l = \text{length}(\text{words})$

**make** maps *best\_score*, *best\_edge*

$\text{best\_score}["0 \text{ <s>}"] = 0$  # Start with <s>

$\text{best\_edge}["0 \text{ <s>}"] = \text{NULL}$

**for**  $i$  in  $0 \dots l-1$ :

**for each** *prev* in keys of *possible\_tags*

**for each** *next* in keys of *possible\_tags*

**if**  $\text{best\_score}["i \text{ prev}"]$  **and**  $\text{transition}["\text{prev next}"]$  **exist**

        score =  $\text{best\_score}["i \text{ prev}"] +$

$-\log P_T(\text{next}|\text{prev}) + -\log P_E(\text{word}[i]|\text{next})$

$w^*(\text{CREATE\_T}(\text{prev},\text{next})+\text{CREATE\_E}(\text{next},\text{word}[i]))$

**if**  $\text{best\_score}["i+1 \text{ next}"]$  **is new or**  $< \text{score}$

$\text{best\_score}["i+1 \text{ next}"] = \text{score}$

$\text{best\_edge}["i+1 \text{ next}"] = "i \text{ prev}"$

# Finally, do the same for </s>

# Exercise

## Exercise

- **Write** `train-hmm-percep` and `test-hmm-percep`
- **Test** the program
  - Input: `test/05- $\{train, test\}$ -input.txt`
  - Answer: `test/05- $\{train, test\}$ -answer.txt`
- **Train** an HMM model on `data/wiki-en-train.norm_pos` and **run** the program on `data/wiki-en-test.norm`
- **Measure** the accuracy of your tagging with  
`script/gradeupos.pl data/wiki-en-test.pos my_answer.pos`
- **Report** the accuracy (compare to standard HMM)
- **Challenge:**
  - create new features
  - use training with margin or regularization

Thank You!